System Health Monitoring and Reactive Measures Activation

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Content

- Definition, components and architecture
- Data Gathering
- Detection
- Prediction
- Risk Assessment
- Prevention

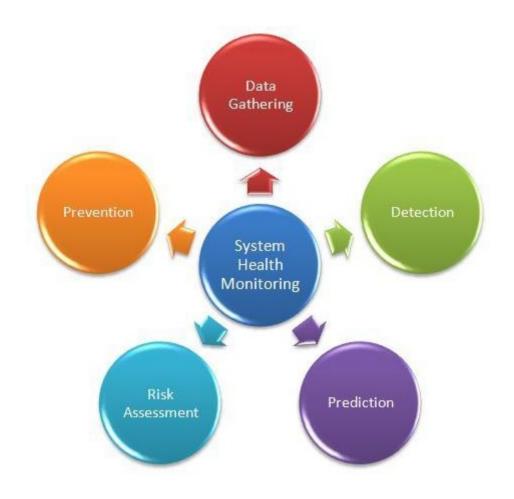


System Health Monitoring and Reactive Measures Activation

Continuously monitor the health of a large system so that system anomalies (bad behaviors and attacks) can be promptly detected and handled appropriately

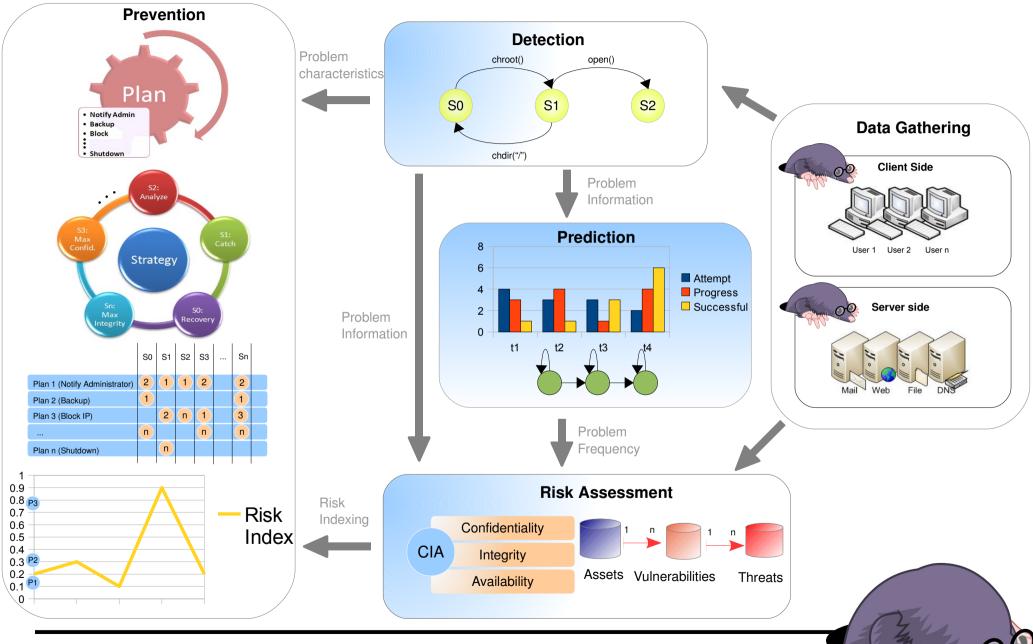


System Health Monitoring Components





System Health Monitoring Architecture

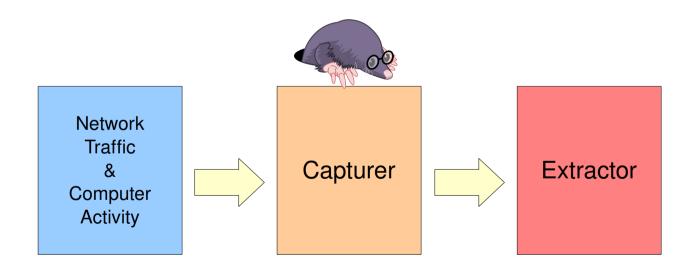


Data Gathering



Data Gathering (1)

- Networking
 - Characterize network connections features.
 - Each TCP/IP connection was described by some authors with up to 41
 quantitative and qualitative features that can be used for anomaly detection.
- System Calls





Data Gathering (2) - Features

 Continuous and discrete features of connections (e.g. service type: TCP, UDP, ICPM)

1	duration	9	urgent	17	num_file_creations	25	serror_rate	33	dst_host_srv_count
2	protocol type	10	hot	18	num_shells	26	srv_serror_rate	34	dst_host_same_srv_rate
3	service	11	num_failed_logins	19	num_access_files	27	rerror_rate	35	dst_host_diff_srv_rate
4	Flag	12	logged_in	20	num_outbound_cmds	28	srv_rerror_rate	36	dst_host_same_src_port_rate
5	src_bytes	13	num_compromised	21	is_host_login	29	same_srv_rate	37	dst_host_srv_diff_host_rate
6	dst_bytes	14	root_shell	22	is_guest_login	30	diff_srv_rate	38	dst_host_serror_rate
7	land	15	su_attempted	23	count	31	srv_diff_host_rate	39	dst_host_srv_serror_rate
8	wrong_fragment	16	num_root	24	srv_count	32	dst_host_count	40	dst_host_rerror_rate
41	dst_host_srv_rerror_rate								

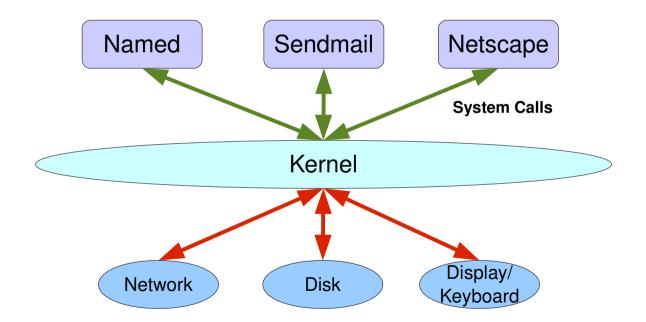
41 features of each TCP/IP connection

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- [2] MIT Lincoln Laboratory. http://www.ll.mit.edu/IST/ideval/
- [3] University of California Irvine Machine Learning Archive. http://kdd.ics.uci.edu/databases/kddcup99/kddcup99.html



Data Gathering (3) - System Calls

• System call trace: open, read, mmap, mmap, open, getrlimit, mmap, close





- [1] MIT Lincoln Laboratory. http://www.ll.mit.edu/IST/ideval/
- [2] University of New Mexico . http://www.cs.unm.edu/~immsec/systemcalls.htm



Detection



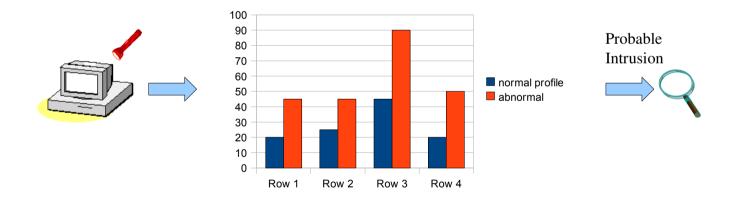
Detection

- Anomaly detection can detect new problems, but it has a higher false positive rate than intrusion detection systems based on attack signatures.
- Most systems concentrate on detecting incorrect network behavior.
- An ideal detection component has a 100% problem detection rate along with a 0% false positive rate.



Anomaly

- There are some profiles that represent normal behavior of users, hosts, or networks
- Anomalies are significant deviations from these profiles





- [1] http://en.wikipedia.org/wiki/Anomaly
- [2] http://en.wikipedia.org/wiki/Anomaly_detection

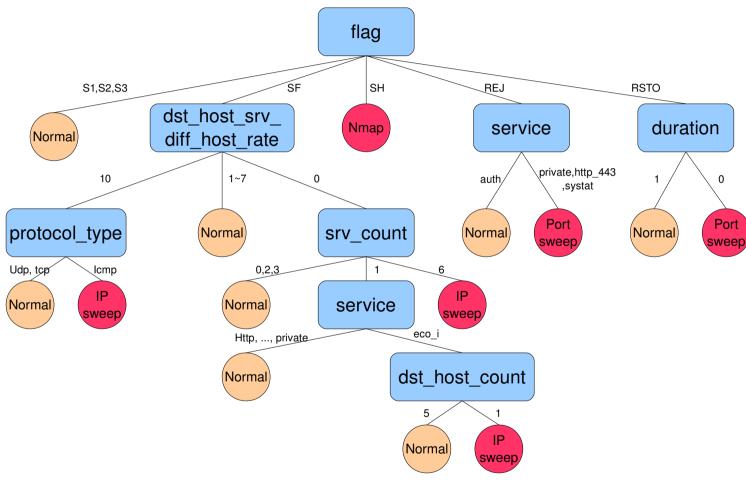


Detection Algorithms (1)

- Decision Tree (DT)
- Fuzzy
- Neural Network
- Support Vector Machines (SVM)
- Bayesian Network
- Hidden Markov Models (HMM)
- Nearest neighbor
- Clustering



Detection Algorithms (2) – Decision Tree

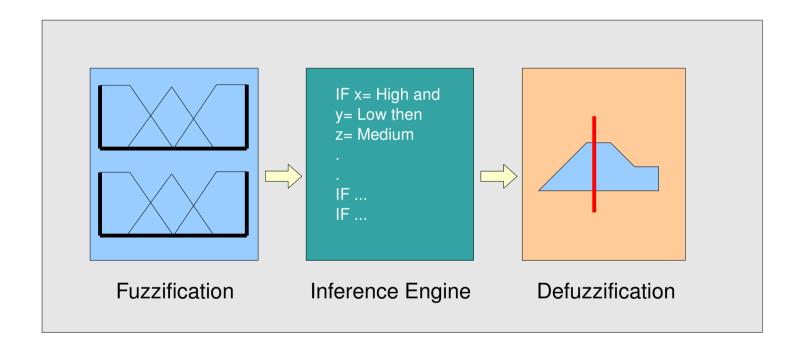




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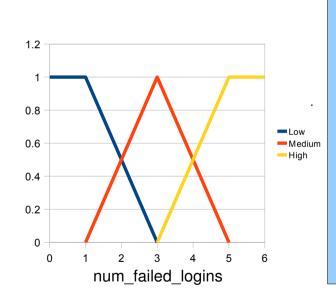
Detection Algorithms (3) – Fuzzy(1)





Detection Algorithms (4) – Fuzzy(2)

- Continuous and discrete features, different fuzzification methods.
- It is very difficult to define the membership function for all the continuous features even for an expert, an automatic approach must be used to create the membership functions for each continuous feature.



Three Level Membership Function

If (dst_host_srv_count is not low or protocol_type is not tcp) and protocol_type is not icmp then normal = High
.....

If (dst_host_srv_count is low and flag is not S0 and and protocol_type is not icmp and dst_host_srv_rerror_rate is not level-4 then

U2R = Medium

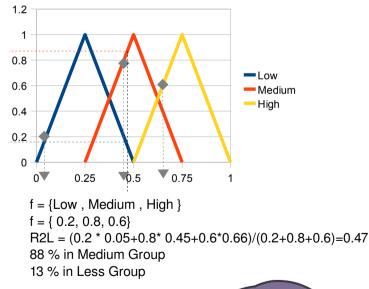
If num_failed_logins is High and logged_in is Low then R2L = Medium

If (dst_host_srv_count is low or is_guest_login is true) and flag is not REJ and dst_host_same_srv_rate is not low and duration is not level-4 then R2L = High

If count is not low or same_srv_rate is low then

fuzzy rule

DOS = High



Defuzzification

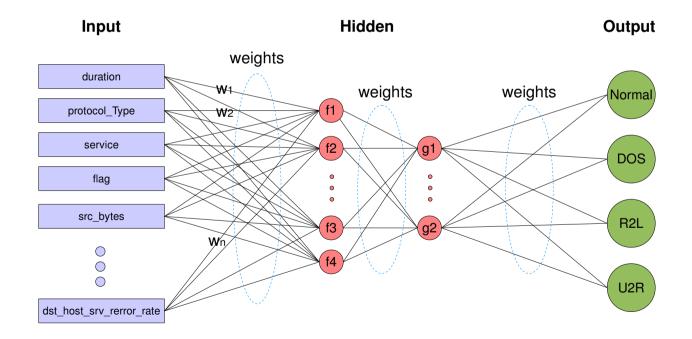
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Detection Algorithms (5) – Neural Network

- Each input into the neuron has its own associated weight, determined by training.
- The weights in most neural nets can be negative or positive.
- f1 = duration * w1+ protocol_type * w2 + ...

•



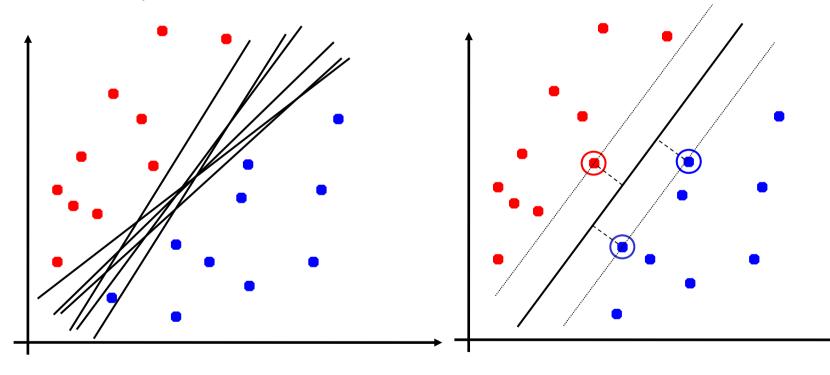


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- [3] Bouzida Y. and Cuppens F., **Neural networks vs. decision trees for intrusion detection**, IEEE / IST Workshop on Monitoring, Germany, September, 2006



Detection Algorithms (6) – Support Vector Machines

- Which of the linear separators is optimal?
- SVM uses a high dimension space to find a hyper-plane to perform binary classification
- SVM can handle the problem of linear inseparability
- For example, 41 features can be used to train SVM model

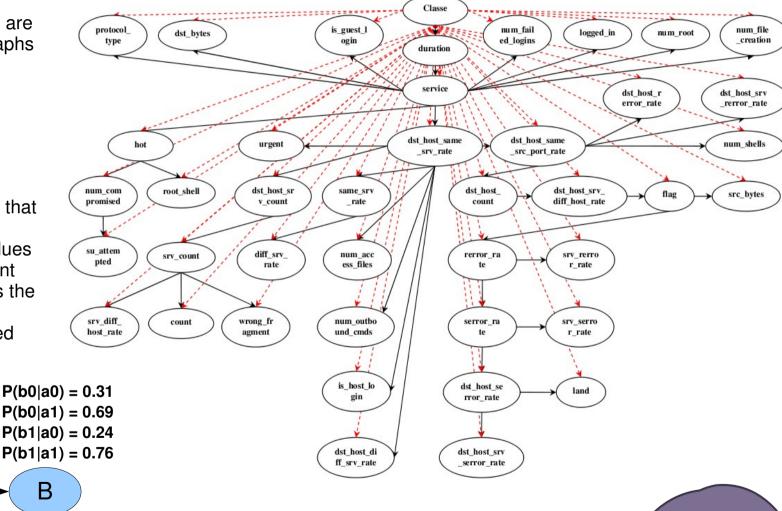


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- [6] Abraham A, Jain R., Thomas J. and Han S. Y., **D-SCIDS: Distributed soft computing intrusion detection system**, Journal of Network and Computer Applications, pp. 81–98, 2007



Detection Algorithms (7) – Bayesian Network

- Bayesian networks are directed acyclic graphs whose nodes represent random variables in the Bayesian sense
- Each node is
 associated with a
 probability function that
 takes as input a
 particular set of values
 for the node's parent
 variables and gives the
 probability of the
 variable represented
 by the node





P(a0) = 0.42

P(a1) = 0.58

- [1] http://en.wikipedia.org/wiki/Bayesian_network
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Detection Algorithms (8) – Hidden Markov Models (1)

- Consider the following sequence of system calls to define normal behavior:
 - Open, read, mmap, mmap, open, getrlimit, mmap, close
- Sliding window = K and suppose k=4
- For the first window, we see (open,read,mmap,mmap) then the following database is produced:

call	position 1	position 2	position 3
open	read	mmap	mmap
read	mmap	mmap	
mmap	mmap		

 After sliding the window across the complete sequence, we produce this expanded database

call	position 1	position 2	position 3
open	read,	mmap	mmap,
	getrlimit		close
read	mmap	mmap	open
mmap	mmap,	open,	getrlimit,
	open,	getrlimit	mmap
	close		
getrlimit	mmap	close	
close			



Detection Algorithms (9) – HMM (2)

- Suppose we have a new trace of calls, differing at one location from the normal sequence (open replaces mmap as the fourth call in the sequence):
 - open, read, mmap, open, open, getrlimit, mmap, close
- This trace would generate 4 mismatches, because:
 - open is not followed by open at position 1
 - open is not followed by open at position 3,
 - read is not followed by open at position 2,
- Mismatches are the only observable that we use to distinguish normal from abnormal

call	position 1	position 2	position 3
open	read,	mmap	mmap,
	getrlimit		close
read	mmap	mmap	open
mmap	mmap,	open,	getrlimit,
	open,	getrlimit	mmap
	close		
getrlimit	mmap	close	
close			
mmap getrlimit	mmap, open, close	open, getrlimit	getrlimit,



Detection Algorithms (10) – HMM (3)

Capture system call trace:

..., open, read, mmap, mmap, open, getrlimit, close, ...

Extract sequences:

n-grams

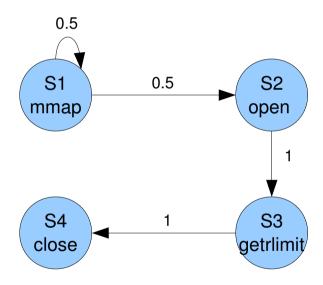
mmap, mmap, open, getrlimit
mmap, open, getrlimit, close

Data Modelling

open, getrlimit mmap, *, getrlimit mmap, *, *, getrlimit getrlimit, close open, *, close mmap, *, *, close

lookahead pairs

State = $\{s1, s2, s3, s4\}$



HMM for two sliding window

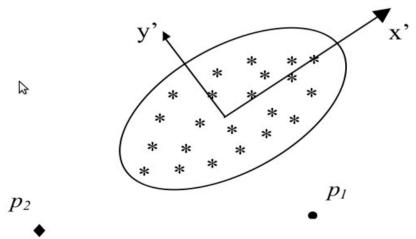


- [1] http://en.wikipedia.org/wiki/Hidden_Markov_model
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Detection Algorithms (11) – Nearest neighbor

- Normal data instances occur in **dense neighborhoods**, while anomalies occur **far from** their closest neighbors
- Distance (or similarity) between two data instances can be computed in different ways
 - Euclidean metric
 - Mahalanobis metric
- We must define a threshold that can be calculated in training phase
- All test data points that have distances to their nearest neighbors greater than the threshold are detected as anomaly





- [1] http://en.wikipedia.org/wiki/K-nearest_neighbor_algorithm
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Detection Algorithms (12) – Clustering

- Different concepts for clustering:
 - Normal data instances belong to a cluster in the data, while anomalies do not belong to any cluster
 - Normal data instances lie close to their closest cluster centroid, while anomalies are far away from their closest cluster centroid
 - Normal data instances belong to large and dense clusters, while anomalies either belong to small or sparse clusters



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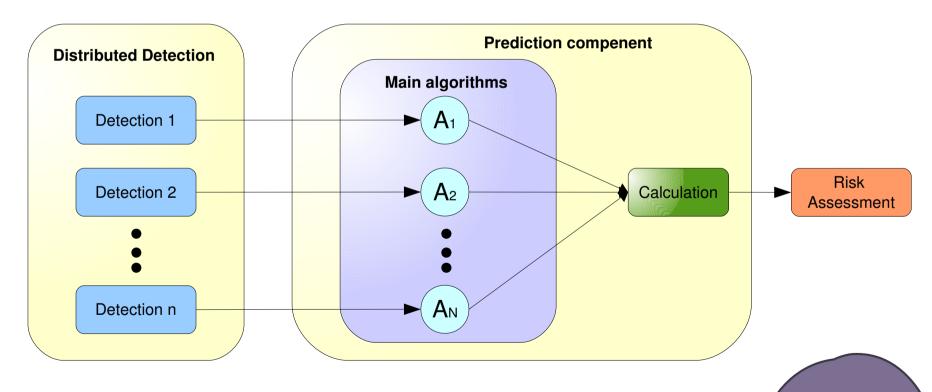


Prediction



Prediction Structure

- The prediction component will attempt to make a prediction of a possible future problem based on the current distributed problem pattern
- The prediction component processes the problem data information from the various detection components

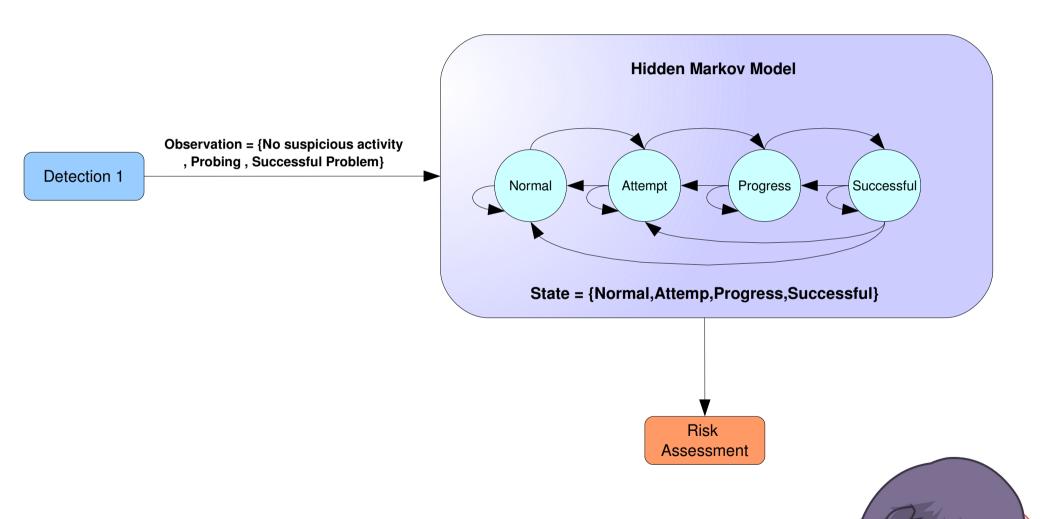


Prediction Algorithms

- Hidden Markov Model (HMM)
- Bayesian Network



Prediction Algorithms-HMM



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Online Risk Assessment



Risk Assessment

- Risk assessment is the process of identifying, characterizing, and understanding risk.
- The result of risk assessment, risk index, provides decision support for the prevention component.
- Risk index in three aspects:
 - The probability that an abnormal activity detected is a true problem
 - The probability that a problem can successfully compromise its target
 - The severity caused by a problem



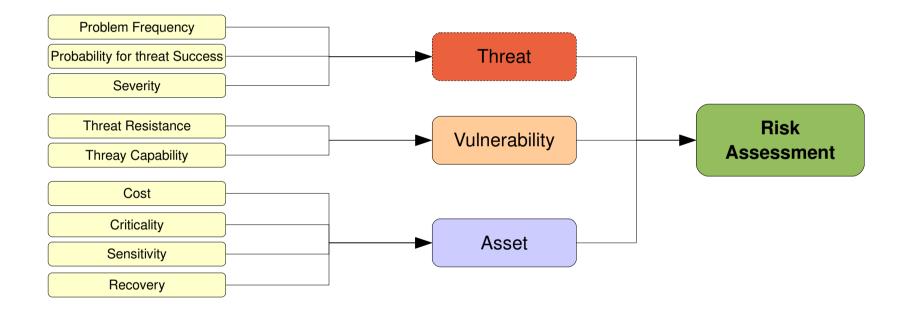
Risk Assessment Methods

- Fuzzy
- Dempster-Shafer (D-S) Evidence Theory
- Hidden Markov Model (HMM)
- Bayes framework
- Rule based (similar to SQL)
- Genetic Programming



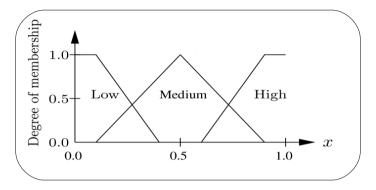
Risk Assessment Methods- Fuzzy (1)

Fuzzy model uses the general structure of risk assessment





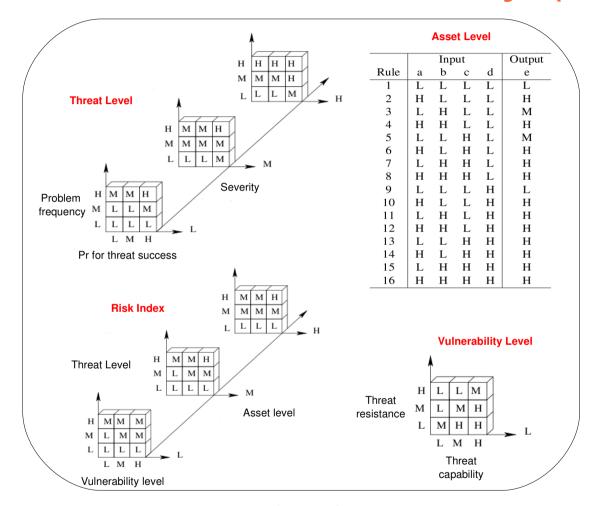
Risk Assessment Methods- Fuzzy (2)



Fuzzification/Defuzzification

1) problem frequency	0.25> L and M
2) Pr threat success	0.90> H
3) severity	0.40> M
Threat level	M> 0.28
1) threat resistance	0.10> L
2) threat capability	0.50> M
Vulnerability level	H> 0.86
1) cost	0.30> L and M
2) criticality	0.70> M and H
3) sensivity	0.15> L and M
4) recovery	0.40> M
Asset level	M> 0.50
Risk index	M> 0.34

Results



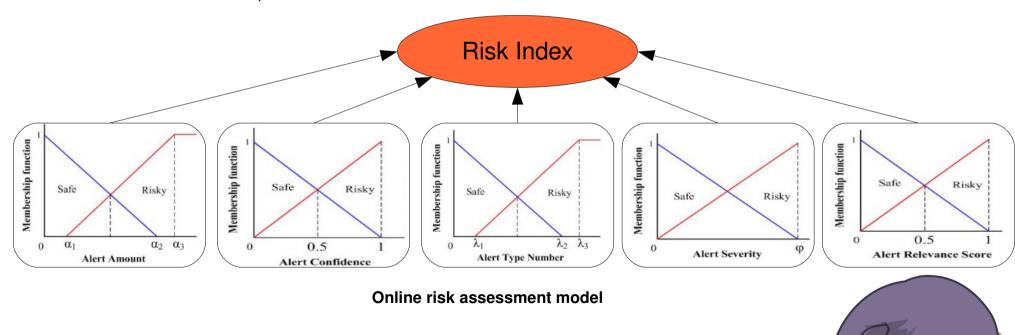
fuzzy rule

Fyzzy model for online risk assessment



Risk Assessment Methods-D-S Evidence Theory

- D-S evidence theory is a frequently used tool in solving complex problems with uncertainties
- D-S evidence concepts:
 - Some evidence is not reliable (the anomaly is wrong sometimes and right sometimes)
 - Some evidence is incorrect.
 - Some evidence is uncertain
 - Some evidence is contradictory
 - Some evidence is incomplete



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Prevention



Prevention Methods

Association Based Systems

 Whenever a specified problem occurs, a response will be triggered.

Expert Based Systems

 Decision making but no learning (i.e. cannot increase their artificial intelligence level during their lifetime).

Adaptive Based Systems

Decision making and learning.



Prevention Structure



Prevention - Plan

- IP Blocking
- Dropping Packets
- Killing Process
- Reboot
- Shutdown
- TCP Reset
- Delete files
- Run Virus Check
- Turn off the services
- Applying Patch

- Change All Passwords
- Format the Hard Disk
- ...
- •



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Conclusion

- Layered, incremental approach from raw monitoring data to reactive measures.
- Build upon automated problem identification and trace abstraction.
- Use both problem descriptions and deviations from normal operation.
- Implement a framework to experiment with several of the best methods proposed in the literature.